Theoretical Convergence Guarantees for Variational Autoencoders

Sobihan Surendran, Antoine Godichon-Baggioni, Sylvain Le Corff

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 - Structured Latent Space: Encourages interpretable and disentangled representations.
 - ► Sample Efficiency: Performs well in low sample size scenarios (e.g., medical imaging).
 - ► Latent Diffusion: VAE-based diffusion models achieves state-of-the-art results in image generation.

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- **Theoretical Understanding:** Prior work has primarily focused on generalization bounds, ELBO approximations, and posterior collapse. However, the **Optimization in VAE remains underexplored**.



- 2 Deep Gaussian VAE
- 3 Importance Weighted Autoencoder
- 4 Extension to Variational Inference

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We consider generative models of the form:

$$p_{\theta}(x) = \int p_{\theta}(z) p_{\theta}(x|z) \mathrm{d}z \; ,$$

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where x is an **observation** and z a **latent variable**. The marginal log-likelihood is given by:

$$\log p_{\theta}(x) = \log \mathbb{E}_{p_{\theta}(\cdot|x)} \left[\frac{p_{\theta}(x,z)}{p_{\theta}(z|x)} \right] \gtrsim \underbrace{\mathbb{E}_{q_{\phi}(\cdot|x)} \left[\log \frac{p_{\theta}(x,z)}{q_{\phi}(z|x)} \right]}_{=: \mathcal{L}(\theta,\phi;x),$$

Evidence Lower Bound (ELBO)

where $q_{\phi}(z|x)$ is the variational distribution.

Optimization in Variational Autoencoders

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 - Score function estimator: general, but high variance.
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Consider the Stochastic Gradient Descent (SGD) update:

$$(\theta_{k+1}, \phi_{k+1}) = (\theta_k, \phi_k) + \gamma_{k+1} \widehat{\nabla}_{\theta, \phi} \mathcal{L}(\theta_k, \phi_k; \mathcal{D}_{k+1}) , \qquad (1)$$

- $\widehat{\nabla}_{\theta,\phi} \mathcal{L}(\theta_k, \phi_k; \mathcal{D}_{k+1})$ denotes an estimator of the gradient,
- \mathcal{D}_{k+1} is the mini-batch of data used at iteration k+1,
- $\gamma_k > 0$ is the learning rate.

The Deep Gaussian VAE consists of a decoder and an encoder such that:

$$\begin{split} p_{\theta}(x|z) &= \mathcal{N}(x; G_{\theta}(z), c^2 \mathbf{I}_{d_x}) \;, \\ q_{\phi}(z|x) &= \mathcal{N}(z; \mu_{\phi}(x), \Sigma_{\phi}(x)) \;. \end{split}$$

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Figure: Architecture of a VAE using multivariate Gaussian distributions.

Convergence Analysis for Deep Gaussian VAE

Consider a Neural Network with the assumptions:

- (i) For all $\phi \in \Phi$, $\lambda_{\min}(\Sigma_{\phi}(x)) \ge c_{\Sigma}$ and all activation functions are Lipschitz continuous and smooth.
- (ii) There exists a constant a such that $\|\theta\|_{\infty} + \|\phi\|_{\infty} \leq a$ for all $\theta \in \Theta$ and $\phi \in \Phi$.

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Convergence Analysis

Let $(\theta_n, \phi_n) \in \Theta \times \Phi$ be the *n*-th iterate of Adam, with $\gamma_n = C_{\gamma} n^{-1/2}$, $C_{\gamma} > 0$, and $\beta_1 < \sqrt{\beta_2} < 1$. For all $n \ge 1$, let $R \sim \mathcal{U}(\{0, \ldots, n\})$. Then,

$$\mathbb{E}\left[\left\|\nabla_{\theta,\phi}\mathcal{L}\left(\theta_{R},\phi_{R}\right)\right\|^{2}\right] = \mathcal{O}\left(\frac{\mathcal{L}^{*}}{\sqrt{n}} + Na^{2(N-1)}\frac{d^{*}\log n}{\left(1-\beta_{1}\right)\sqrt{n}}\right)$$

where $\mathcal{L}^* = \mathcal{L}(\theta^*, \phi^*) - \mathcal{L}(\theta_0, \phi_0)$, $d^* = d_{\theta} + d_{\phi}$ is the dimension of the parameters, and N is the number of layers in the encoder and decoder.

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Illustration of Our Convergence Rate

♦ Generalized Soft-Clipping (Lipschitz, smooth, and bounded between s₁ and s₂):

$$f(x) = \frac{1}{s} \log \left(\frac{1 + e^{s(x-s_1)}}{1 + e^{s(x-s_2)}} \right) + s_1 .$$

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Figure: Squared norm of gradients and Negative ELBO on CelebA for VAE trained with Adam.

Objective: Obtain a **tighter ELBO** by using multiple importance weighted samples:

$$\log p_{\theta}(x) \geq \underbrace{\mathbb{E}_{q_{\phi}^{\otimes K}(\cdot|x)}\left[\log \frac{1}{K} \sum_{\ell=1}^{K} \frac{p_{\theta}(x, z^{(\ell)})}{q_{\phi}(z^{(\ell)}|x)}\right]}_{\text{IWAE}} \geq \underbrace{\mathbb{E}_{q_{\phi}(\cdot|x)}\left[\log \frac{p_{\theta}(x, z)}{q_{\phi}(z|x)}\right]}_{\text{VAE}}$$

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Convergence Analysis (Informal)

Under similar assumptions to those for VAE, we have:

$$\mathbb{E}\left[\left\|\nabla_{\theta,\phi}\mathcal{L}_{K}^{\mathsf{IWAE}}\left(\theta_{R},\phi_{R}\right)\right\|^{2}\right] = \mathcal{O}\left(\frac{\mathcal{L}_{K}^{*}}{\sqrt{n}} + d^{*}\frac{\log n}{BK\sqrt{n}}\right) \;,$$

where B is the batch size and K is the number of variational samples.

Illustration of Our Convergence Rate in IWAE



Figure: Negative ELBO in IWAE on CelebA and CIFAR-100 trained with Adam.

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Link with Signal-to-Noise Ratio (SNR) [Rainforth et al. 2018]. SNR: expected gradient magnitude scaled by its standard deviation. $SNR(\theta) = \sqrt{BK} \quad SNR(\phi) = \sqrt{B/K}$

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 \Rightarrow Gradually increase K until a fixed threshold is reached.

⇒ Use **Rényi IWAE** [Daudel et al. 2023] with SNR(θ, ϕ) = \sqrt{BK} .

Extension to Variational Inference

• Variational Inference is typically formulated as:

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\phi^* \in \operatorname*{argmin}_{\phi \in \Phi} \mathsf{KL}(q_\phi \, \| \, p(\cdot | x))
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Reference	Non-Concavity of $\log p$	Beyond Location-Scale Family for q_{ϕ}	Parameterization Type
Kim et al. 2024	×	X	Linear
Domke et al. 2023	\checkmark	×	Linear
Kim et al. 2023	\checkmark	×	Non-linear (scale)
Ours	\checkmark	\checkmark	Non-linear

Structural Assumptions in Prior Convergence Results.

Location-Scale Family: Distributions obtained by shifting and scaling a fixed base distribution, i.e., $Y = \mu + \sigma W$ with location μ and scale $\sigma > 0$.

- A convergence rate of $\mathcal{O}(n^{-1/2} \log n)$ for VAE with SGD and Adam, illustrated using the Deep Gaussian VAE.
- Increasing K in **IWAE** without tuning other parameters leads to vanishing SNR and poor gradient estimates for ϕ , hindering the learning of θ .
- New convergence results for **Variational Inference**, beyond location-scale families and linear parameterizations.

References

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Thank you for your attention!



Find the full paper here (Accepted at AISTATS 2025)