

Theoretical Convergence Guarantees for Variational Autoencoders



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Goal

Provide a non-asymptotic analysis of Variational Autoencoders and Importance Weighted Autoencoders with Stochastic Gradient Descent.

Series Establish theoretical guarantees and illustrate the results using **Deep Gaussian VAE**.

Reference Extend the analysis to Black Box Variational Inference.

Importance Weighted Autoencoder

Objective: Obtain a tighter ELBO by using multiple importance-weighted samples:



Introduction

We consider generative models of the form $p_{\theta}(x, z) = p_{\theta}(z) p_{\theta}(x|z)$, where x is an observation and z a latent variable. The marginal log-likelihood is given by:

$$\log p_{\theta}(x) = \log \mathbb{E}_{p_{\theta}(\cdot|x)} \left[\frac{p_{\theta}(x,z)}{p_{\theta}(z|x)} \right] \ge \mathbb{E}_{q_{\phi}(\cdot|x)} \left[\log \frac{p_{\theta}(x,z)}{q_{\phi}(z|x)} \right] =: \mathcal{L}(\theta,\phi;x) ,$$

Evidence Lower Bound

where $q_{\phi}(z|x)$ is the variational distribution.

The Pathwise Gradient.

▶ Reparameterization trick [1]: z = g(ε, φ), where ε ~ p_ε (known distribution).
▶ Pathwise gradient of the ELBO:

 $\nabla_{\phi} \mathcal{L}(\theta, \phi; x) = \mathbb{E}_{p_{\varepsilon}} \left[\nabla_{z} \log w_{\theta, \phi}(x, z) \cdot \nabla_{\phi} g(\varepsilon, \phi) \right] - \mathbb{E}_{p_{\varepsilon}} \left[\nabla_{\phi} \log q_{\phi}(g(\varepsilon, \phi) \mid x) \right] ,$

where $w_{\theta,\phi}(x,z) = p_{\theta}(x,z)/q_{\phi}(z|x)$ the unnormalized importance weights.

Consider the **Stochastic Gradient Descent (SGD)** update:

$$\boldsymbol{\theta}_{k+1}, \boldsymbol{\phi}_{k+1}) = (\boldsymbol{\theta}_k, \boldsymbol{\phi}_k) + \gamma_{k+1} \widehat{\nabla}_{\boldsymbol{\theta}, \boldsymbol{\phi}} \mathcal{L}(\boldsymbol{\theta}_k, \boldsymbol{\phi}_k; \mathcal{D}_{k+1}) , \qquad (1)$$

where $\widehat{\nabla}_{\theta,\phi} \mathcal{L}(\theta_k, \phi_k; \mathcal{D}_{k+1})$ denotes an estimator of the gradient, \mathcal{D}_{k+1} is the mini-batch of data used at iteration k+1 and for all $k \ge 1$, $\gamma_k > 0$ is the learning rate.

Smoothness of \mathcal{L} + Gradient variance bound $\Rightarrow \mathbb{E}\left[\|\nabla \mathcal{L}(\theta_n, \phi_n)\|^2 \right] = \mathcal{O}(n^{-1/2} \log n).$

Convergence Analysis for IWAE

Assuming the same conditions as for VAE and mild regularity on weights $w_{ heta,\phi}$, we have:

$$\mathbb{E}\left[\left\|\nabla_{\theta,\phi}\mathcal{L}_{K}^{\mathsf{IWAE}}\left(\theta_{R},\phi_{R}\right)\right\|^{2}\right] = \mathcal{O}\left(\frac{\mathcal{L}^{*}}{\sqrt{n}} + d^{*}\frac{\log n}{BK\sqrt{n}}\right)$$

where B is the batch size and K is the number of variational samples.

Link with Signal-to-Noise Ratio (SNR) [2]. SNR: expected gradient magnitude scaled by its standard deviation. $SNR(\theta) = \sqrt{BK} \quad SNR(\phi) = \sqrt{B/K}$



Figure: Negative ELBO in IWAE on CelebA (on the left) and CIFAR-100 (on the right) trained with Adam.

Deep Gaussian VAE



Figure: Illustration of the Architecture of a VAE using multivariate Gaussian distributions.

Convergence Analysis for Deep Gaussian VAE

Consider a neural network with the assumptions:

(i) $||G_{\theta}(z)|| \leq C_G$, $||\mu_{\phi}(x)|| \leq C_{\mu}$, $\lambda_{\min}(\Sigma_{\phi}(x)) \geq c_{\Sigma}$, and all activation functions are Lipschitz continuous and smooth.

(ii) There exists a constant a such that $\|\theta\|_{\infty} + \|\phi\|_{\infty} \leq a$ for all $\theta \in \Theta$ and $\phi \in \Phi$.

Let $(\theta_n, \phi_n) \in \Theta \times \Phi$ be the *n*-th iterate of Adam, with $\gamma_n = C_{\gamma} n^{-1/2}$, $C_{\gamma} > 0$, and $\beta_1 < \sqrt{\beta_2} < 1$. For all $n \ge 1$, let $R \in \{0, \ldots, n\}$ be a uniformly distributed random variable. Then,

$$\mathbb{E}\left[\left\|\nabla_{\theta,\phi}\mathcal{L}\left(\theta_{R},\phi_{R}\right)\right\|^{2}\right] = \mathcal{O}\left(\frac{\mathcal{L}^{*}}{\sqrt{n}} + Na^{2(N-1)}\frac{d^{*}\log n}{\left(1-\beta_{1}\right)\sqrt{n}}\right),$$

where $\mathcal{L}^* = \mathcal{L}(\theta^*, \phi^*) - \mathcal{L}(\theta_0, \phi_0)$, $d^* = d_\theta + d_\phi$ is the total dimension of the parameters,

 \Rightarrow gradually increase K until a threshold, or use Rényi IWAE with SNR $(\theta, \phi) = \sqrt{BK}$.

Extension to Black Box Variational Inference

Black Box Variational Inference (BBVI) is typically formulated as:

$$\phi^* \in \operatorname*{argmin}_{\phi \in \Phi} \mathsf{KL}(q_\phi \| p(\cdot | x)) \iff \phi^* \in \operatorname*{argmax}_{\phi \in \Phi} \mathbb{E}_{q_\phi(\cdot | x)} \left[\log \frac{p(x, z)}{q_\phi(z | x)} \right]$$

where $q_{\phi}(z|x)$ is the variational distribution.

Structural Assumptions in Prior Convergence Results.

Reference	Non-Concavity	Beyond Location-Scale	Parameterization
	of $\log p$	Family for q_{ϕ}	Туре
Kim et al. [3]	×	×	Linear
Domke et al. [4]	\checkmark	×	Linear
Kim et al. [5]	\checkmark	×	Non-linear (scale)
Ours	\checkmark	\checkmark	Non-linear

Conclusion

EVANCE A convergence rate of $\mathcal{O}(n^{-1/2} \log n)$ for **VAE** with **SGD** and **Adam**.

Illustration of the results using the Deep Gaussian VAE, that supports our theoretical claims, with similar empirical results for standard VAE with ReLU.

and N is the total number of layers in the encoder and decoder.

• Generalized Soft-Clipping (Lipschitz, smooth, and bounded between s_1 and s_2):

 $f(x) = \frac{1}{s} \log \left(\frac{1 + e^{s(x - s_1)}}{1 + e^{s(x - s_2)}} \right) + s_1 .$



Figure: Squared norm of gradients and Negative ELBO on CelebA for VAE trained with Adam.

Increasing K in **IWAE** without tuning other parameters leads to vanishing SNR and poor gradient estimates for ϕ , hindering the learning of θ .

Rev Convergence results for **BBVI**, beyond location-scale families and linear parameterizations.

References

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